

# Stability Considerations using a Chapman-Enskog-like (CEL) kinetic closure approach in NIMROD

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- We have succeeded in eliminating an "instability" caused by numerical errors in  $\mathbf{b}_{\text{eq}} \cdot \nabla T_{i,\text{eq}}$ .
- We are working on eliminating another numerical instability in coupled fluid-kinetic runs.
- A stability analysis is being undertaken for the coupled system that is similar to (Sovinec & King 2010)<sup>1</sup>.

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<sup>1</sup>C. Sovinec and J. King, "Analysis of a mixed semi-implicit/implicit algorithm for low-frequency two-fluid plasma modeling", *Journal of Computational Physics* **229**, 5803–5819 (2010) 

# Kinetics allows for more rigorous closure of the plasma fluid equations

- Without kinetics only heuristic closures can be specified; however, if one has the kinetic distribution function, rigorous closure is possible.
- As an example, to lowest order in  $\delta \equiv \rho_{\text{Larmor}}/L$  (with  $L =$  macroscopic length scale), the definition of the ion viscous stress tensor is  $\mathbf{\Pi}_i = \pi_{i\parallel}(\mathbf{b}\mathbf{b} - \mathbf{I}/3)$ , where  $\mathbf{I}$  is the identity tensor and:

$$\pi_{i\parallel} = m_i \int d^3v v^2 P_2(v_{\parallel}/v) f_i = (p_{i\parallel} - p_{i\perp}),$$

where  $P_2(v_{\parallel}/v)$  is the second-order Legendre polynomial in  $v_{\parallel}/v$ , and  $f_i$  is the ion kinetic distribution function.

- We also note that the form of  $\mathbf{q}_i$  to lowest order in  $\delta$  is

$$\mathbf{q}_i = q_{i\parallel} \hat{\mathbf{b}} + \left( \frac{5n_i T_i}{2eB} \mathbf{b} \times \nabla T_i \right), \text{ where}$$

$$q_{i\parallel} = \int d^3v (mv^2/2) v_{\parallel} f_i.$$

# The Chapman-Enskog-like approach avoids inconsistencies by assuming the distribution function is not far from a local Maxwellian

- Spirit of the Chapman-Enskog method [2]:
  - 1 In a magnetized fusion plasma the kinetic distribution function is not far from a local Maxwellian.
  - 2 The local Maxwellian depends on both space and time through the thermodynamic parameters  $n$ ,  $T$ , and  $\mathbf{v}$ .
    - (this differs from traditional  $\delta f$  which assumes only non-time-evolving equilibrium fluid variables in the Maxwellian)
  - 3 This can be succinctly stated as:  $f \approx f_M + f_1$  where  $f_M$  is a flow-shifted time-evolving Maxwellian ( $f_M(\mathbf{x}, t) = \frac{n(\mathbf{x}, t)}{\pi^{3/2}(v_T(\mathbf{x}, t))^3} \exp(-\frac{(\mathbf{v}-\mathbf{u}(\mathbf{x}, t))^2}{(v_T(\mathbf{x}, t))^2})$ ), with  $v_T(\mathbf{x}, t) = \sqrt{2T(\mathbf{x}, t)/m}$ , and  $f_1$  is a first-order (in  $\delta$ ) non-Maxwellian perturbation.



# Full Chapman-Enskog-like kinetic equation can be derived by substituting in the fluid equations for $\partial f_{Mi}/\partial t$ [3]

$$\begin{aligned} \frac{\partial f_{NMi}}{\partial t} + \xi s v_{Ti} \mathbf{b} \cdot \nabla f_{NMi} - \frac{1 - \xi^2}{2\xi} \left[ \xi s v_{Ti} \left( \mathbf{b} \cdot \nabla \ln B - \frac{\mathbf{b} \cdot \nabla \ln n_i}{s^2} \right) \right] \frac{\partial f_{NMi}}{\partial \xi} \\ + \left[ \frac{\xi v_{Ti}}{2} \left( \mathbf{b} \cdot \nabla \ln n - s^2 \mathbf{b} \cdot \nabla \ln T_i \right) \right] \frac{\partial f_{NMi}}{\partial s} - C(f_{NMi}) = \\ \left\{ \frac{\xi s v_{Ti}}{T_i} \left( \frac{5}{2} - s^2 \right) \mathbf{b} \cdot \nabla T_i + \frac{\xi s v_{Ti}}{n_i T_i} \left[ \frac{2}{3} \mathbf{b} \cdot \nabla (\rho_{i\parallel} - \rho_{i\perp}) - (\rho_{i\parallel} - \rho_{i\perp}) \mathbf{b} \cdot \nabla \ln B \right] + P_2(\xi) \frac{2}{3} s^2 (\nabla \cdot \mathbf{u}_i - \right. \\ \left. 3 \mathbf{b} \cdot [\mathbf{b} \cdot \nabla \mathbf{u}_i]) + \frac{2}{3 n_i T_i} \left( s^2 - \frac{3}{2} \right) \nabla \cdot (q_{i\parallel} \mathbf{b}) + \left[ -\frac{2}{3} s^2 P_2(\xi) \left( \left( s^2 - \frac{5}{2} \right) (2\kappa - \nabla \ln B) + \nabla \ln n_i \right) - \right. \\ \left. \left. \frac{4}{3} \left( \frac{1}{2} s^4 - \frac{5}{2} s^2 + \frac{15}{8} \right) (\kappa + \nabla \ln B) \right] \cdot \left( \frac{\nabla T_i \times \mathbf{b}}{eB} \right) \right\} f_{NMi} \end{aligned}$$

- Velocity defined to be in macroscopic flow reference frame.
- $s \equiv v/v_{Ti}$ ,  $\xi \equiv v_{\parallel}/v$ , and  $C$  is the full linearized Fokker-Planck Coulomb collision operator
- $\kappa = \hat{\mathbf{b}} \cdot \nabla \hat{\mathbf{b}}$
- Full CEL approach requires coupling to fluid evolution equations for  $n_i$ ,  $T_i$ , and  $\mathbf{u}_i$ , (and an Ohm's law for  $\mathbf{B}$ ).

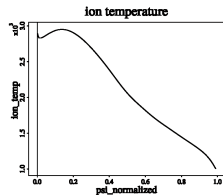
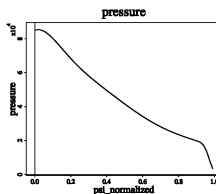
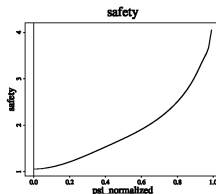
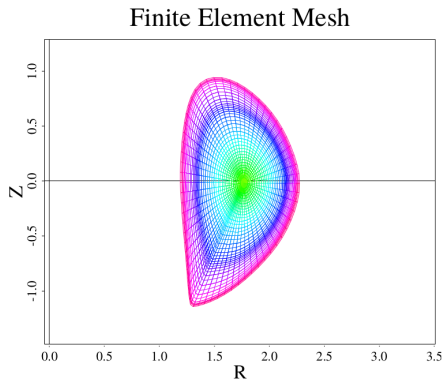


# An initial test of the full CEL approach involves the full coupled system in axisymmetric geometry with no equilibrium flow

- Requires coupling the kinetic equation to the fluid evolution equations for  $n_i$ ,  $\mathbf{u}_i$ ,  $T_i$ , and  $T_e$ .
- Resistive MHD Ohm's law:  $\mathbf{E} = -\mathbf{u} \times \mathbf{B} + \eta \mathbf{J}$ .
- Temperature-dependent resistivity:  $\eta = \eta_0 (T_{\text{ref}}/T_{e,n=0})^{3/2}$ , where  $\eta_0$  is a reference resistivity,  $T_{\text{ref}}$  is a constant reference temperature, and  $T_{e,n=0}$  is the axisymmetric electron temperature.
- We also use a small amount of isotropic diffusion,  $D\nabla^2$ , in all equations.
- For a first test, we initialize the equilibrium flows to 0 and then perturb the flow slightly at  $t = 0$ .



# We use a DIII-D equilibrium (DIII-D Iter-Baseline-Scenario (IBS) discharge 174446 at 3390 ms) to test the CEL formulation



- x-point packing makes the grid slightly non-flux aligned



## We have found it is important to remove the $\mathbf{b}_{\text{eq}} \cdot \nabla T_{i,\text{eq}}$ part of the moment terms on the RHS of the kinetic equation

- In the  $\mathbf{b} \cdot \nabla \{ (\rho_{i\parallel} - \rho_{i\perp}), q_{i\parallel} \}$  drives on the RHS of the kinetic equation, there are subtle  $\mathbf{b}_{\text{eq}} \cdot \nabla T_{i,\text{eq}}$  parts included because both  $(\rho_{i\parallel} - \rho_{i\perp})$  and  $q_{i\parallel}$  depend on  $T_i$  (and we are doing currently the equivalent of a `transfer_eq=.true.` for the kinetic equation).
- Explicitly omitting the  $\mathbf{b}_{\text{eq}} \cdot \nabla T_{i,\text{eq}}$  parts of those terms prevents large numerical errors from washing out the solution after about 100 time-steps.
- I am able to run  $\sim 10$  times as far if I omit the  $\mathbf{b}_{\text{eq}} \cdot \nabla T_{i,\text{eq}}$  parts from these drive terms.





# Stability analysis for the coupled system is now underway

- Analysis assumes that all equilibrium quantities are uniform in space, with a uniform background magnetic field pointing in the y-z plane.
- We also assume only small perturbations about equilibrium for the perturbed variables.
- We then Fourier transform all linearized equations, and assume  $\hat{\mathbf{k}} = \hat{\mathbf{y}}$  (i.e. that the wavevector is in the y direction).
- To deal with with the velocity space dependence of the kinetic equation, we first expand  $f_{j1,k}$  as

$$f_{j1,k} = \sum_{l,m} \bar{f}_{lm,k} P_l(\xi) L_m(s) e^{-s^2},$$

where  $P_l(\xi)$  are Legendre polynomials and  $L_m(s)$  are speed polynomials orthonormal with respect to the weight function  $e^{-s^2}$ .

- We then integrate the kinetic equation by  $P_{l'}(\xi)$  and  $L_{m'}(s)$ . This then gives us a set of equations for  $\bar{f}_{lm,k}$  which we truncate at some max  $l$  and  $m$ .

continued . . .



# Stability analysis for the coupled system is now underway (continued)

- Solving for the eigenvalues of the timestep operator then allows one to observe numerical growth and damping rates. Specifically we assume  $\mathbf{u}_k^{j+1} = \lambda \mathbf{u}_k^j$ , where  $j$  represents the timestep, and  $\mathbf{u}_k$  is a vector of all the perturbed quantities.
- This is currently implemented in matlab.



# Conclusions/Future Work

## Conclusions:

- Substantial progress has been made in incorporating the Chapman-Enskog-like approach into NIMROD for Tokamak applications.
- The solely kinetic aspects of the CEL approach have been successfully benchmarked.

## Current/Future Work:

- Von Nuemann stability analysis of the full coupled system is currently underway.
- Verifying the full implementation through comparison with other codes/analytcs/experiment, etc.
- Incorporate poloidal flow damping physics into a non-trivial nonlinear extended MHD calculation, continuing previous work done in NIMROD on the time-dependent field error induced reconnection problem [4], (i.e. Move to full toroidal geometry, and use our improved closure scheme for  $\Pi_i$ ).



# References

- <sup>1</sup> C. Sovinec and J. King, “Analysis of a mixed semi-implicit/implicit algorithm for low-frequency two-fluid plasma modeling”, *Journal of Computational Physics* **229**, 5803–5819 (2010).
- <sup>2</sup> J. P. Wang and J. D. Callen, “Fluid/kinetic hybrid moment description of plasmas via a chapman–enskog-like approach”, *Physics of Fluids B: Plasma Physics* **4**, 1139–1151 (1992).
- <sup>3</sup> J. J. Ramos, *Phys. Plasmas* **17**, 082502 (2010).
- <sup>4</sup> M. T. Beidler, J. D. Callen, C. C. Hegna, and C. R. Sovinec, “Mode penetration induced by transient magnetic perturbations”, *Physics of Plasmas* **25**, 082507 (2018).

