

Application of continuum drift kinetics to parallel heat transport*

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Continuum kinetic physics have been incorporated into NIMROD

Qualities of Chapman-Enskog like (CEL) method*:

- ▶ Separates fluid and kinetic parts of distribution function
- ▶ Fluid equations govern lowest order fluid quantities, n_a , \mathbf{V}_a , and T_a
- ▶ Kinetic equation governs kinetic distortion, F_a
- ▶ n_a , \mathbf{V}_a , and T_a provide thermodynamic drives for F_a
- ▶ Moments of F_a close fluid equations

Research Objective: Understand challenges

- ▶ Strong nonlinear coupling between fluid and F_a
- ▶ Scaling velocity by thermal speed
- ▶ Implicit advance for large time steps

*S. Chapman and T.G. Cowling, *The Mathematical Theory of Non-Uniform Gases* (Cambridge University Press, Cambridge, 1939); Z. Chang and J.D. Callen, *Phys. Fluids* **4**, 1167 (1992).

CEL method separates fluid and kinetic physics

Starting from the DKE* project out Maxwellian part, $f = f^M + F$,
and transform to coordinates, $(s, \xi) \equiv (|\mathbf{v} - \mathbf{V}|/v_T, \mathbf{v} \cdot \mathbf{B}/|\mathbf{v}||\mathbf{B}|)$:

$$\frac{\partial F}{\partial t} + \mathbf{v}_{gc} \cdot \nabla F + \dot{s} \frac{\partial F}{\partial s} + \dot{\xi} \frac{\partial F}{\partial \xi} = C - f^M \left[\frac{d \ln n}{dt} + \frac{2\mathbf{s}}{v_T} \cdot \frac{d\mathbf{V}}{dt} + \left(s^2 - \frac{3}{2} \right) \frac{d \ln T}{dt} \right]$$

where

$$\begin{aligned} \mathbf{v}_{gc} &= v_T s \xi \mathbf{b} + \frac{\mathbf{E} \times \mathbf{B}}{B^2} + \frac{T s^2}{q B} (1 + \xi^2) \mathbf{b} \times \nabla \ln B \\ &\quad + \frac{2T s^2}{q B^2} \left[\xi^2 (\mathbf{I} - \mathbf{b}\mathbf{b}) + \frac{1}{2} (1 - \xi^2) \mathbf{b}\mathbf{b} \right] \cdot \nabla \times \mathbf{B} + \frac{m v_T s \xi}{q B^2} \mathbf{b} \times \frac{\partial \mathbf{B}}{\partial t} \\ \dot{s} &= -\frac{s}{2} \frac{d \ln T}{dt} + \frac{s(1 - \xi^2)}{2} \frac{\partial \ln B}{\partial t} + \frac{q \mathbf{v}_{gc} \cdot \mathbf{E}}{2sT} \\ \dot{\xi} &= \frac{1 - \xi^2}{2\xi} \left\{ -\xi^2 \frac{\partial \ln B}{\partial t} + (\mathbf{v}_{\parallel} + \mathbf{v}_c^*) \cdot \left(\frac{q\mathbf{E}}{T s^2} - \nabla \ln B \right) + \xi^2 \frac{\mathbf{E} \times \mathbf{B}}{B^2} \cdot \nabla \ln B \right. \\ &\quad \left. - \frac{\xi^2}{B^2} [\mathbf{b}\mathbf{b} \cdot (\nabla \times \mathbf{B})] \cdot \mathbf{E} - 2 \frac{T s^2 \xi^2}{q} \mathbf{b} \cdot \nabla \left[\frac{\mathbf{b} \cdot (\nabla \times \mathbf{B})}{B^2} \right] + \frac{m v_T s \xi}{q B} \nabla \cdot \left(\mathbf{b} \times \frac{\partial \mathbf{b}}{\partial t} \right) \right\} \\ \mathbf{v}_c^* &= \frac{2T s^2 \xi^2}{q B^2} (\mathbf{I} - \mathbf{b}\mathbf{b}) \cdot \nabla \times \mathbf{B} + \frac{m v_T s \xi}{q B^2} \mathbf{b} \times \frac{\partial \mathbf{B}}{\partial t} \end{aligned}$$

* R.D. Hazeltine, Plasma Phys. **15**, 77 (1973); R.D. Hazeltine and J.D. Meiss, *Plasma Confinement* (Adisson-Wesley, Redwood City, 1992); J. J. Ramos, Phys Plasmas **17**, 082502 (2010).

Discretization based on NIMROD's spatial and novel velocity representation*

NIMROD's **spatial representation**:

$$F(R, Z, \phi, s, \xi, t) = \sum_i F_{i,n=0}(s, \xi, t) \alpha_{i,n=0} + 2\Re e \left[\sum_{i,n>0} F_{i,n}(s, \xi, t) \alpha_{i,n} \right]$$

Pitch-angle discretization uses finite element method:

$$F_{i,n}(s, \xi, t) = \sum_l F_{i,n,l}(s, t) P_l(\xi)$$

Speed discretization uses collocation method with polynomial expansion:

$$F_{i,n,l}(s, t) \equiv e^{-s^2} \sum_k F_{i,n,l,k}(t) L_k(s) \quad (1)$$

where collocation points and polynomials, $L_k(s)$, are abscissa and polynomials of non-standard quadrature scheme with weight function e^{-s^2} and orthogonality :

$$\int_0^\infty ds L_k(s) L_{k'}(s) e^{-s^2} = \delta_{kk'}$$

*E. D. Held, *et al*, Phys Plasmas **22**, 032511 (2015).

Challenges highlighted in kinetic thermal transport case studies

$$\frac{3}{2}n \frac{\partial T}{\partial t} = \kappa_{\perp} \nabla \cdot [(\mathbf{I} - \mathbf{b}\mathbf{b}) \cdot \nabla T] - \nabla \cdot \mathbf{q}_{\parallel} + Q$$

Calculate parallel heat flux as moment of kinetic distortion

$$\mathbf{q}_{\parallel} = \frac{m}{2} \int d\mathbf{v} v^2 v_{\parallel} F = \pi m v_T^6 \int_{-1}^1 d\xi \int_0^{\infty} ds (s^5 \xi F)$$

$$\begin{aligned} & \frac{\partial F}{\partial t} + \mathbf{v}_{\parallel} \cdot \nabla F - \frac{1 - \xi^2}{2\xi} \mathbf{v}_{\parallel} \cdot \nabla \ln B \frac{\partial F}{\partial \xi} - \frac{s}{2} \left(\mathbf{v}_{\parallel} \cdot \nabla + \frac{\partial}{\partial t} \right) \ln T \frac{\partial F}{\partial s} \\ & = C + \left(\frac{5}{2} - s^2 \right) \mathbf{v}_{\parallel} \cdot \nabla \ln T f^M + \frac{2}{3nT} \left(s^2 - \frac{3}{2} \right) (\nabla \cdot \mathbf{q}_{\parallel} - Q) f^M \end{aligned}$$

(red terms have temperature dependence.)

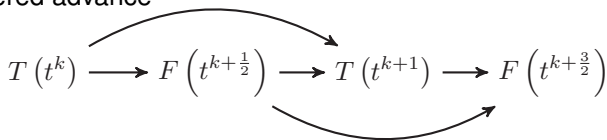
Possible θ -centered semi-implicit time advances

Problem: tight nonlinear coupling of fluid and kinetic distortion

$$\begin{aligned}\frac{\partial T}{\partial t} &= G(T, F) \\ \frac{\partial F}{\partial t} &= H(T, F)\end{aligned}$$

complex nonlinear combinations of T and F

- Staggered advance



$$\Delta T - \theta \Delta t G_{\text{lin}}(\Delta T, F^{k+\frac{1}{2}}) = \Delta t G(T^k, F^{k+\frac{1}{2}})$$

$$\Delta F - \theta \Delta t H_{\text{lin}}(T^{k+1}, \Delta F) = \Delta t H(T^{k+1}, F^{k+\frac{1}{2}})$$

- Simultaneous advance (**Picard iterations** or **Newton iterations**)

$$T(t^k), F(t^k) \longrightarrow T(t^{k+1}), F(t^{k+1})$$

$$\begin{aligned}\Delta T - \theta \Delta t G(T^{k+1}, F^{k+1}) &= (1 - \theta) \Delta t G(T^k, F^k) \\ \Delta F - \theta \Delta t H(T^{k+1}, F^{k+1}) &= (1 - \theta) \Delta t H(T^k, F^k)\end{aligned}$$

GMRES fails to solve

Test case 1: Anisotropic thermal conduction*

Step 1. Impose $\mathbf{E} = E_0 \cos(\pi x) \cos(\pi y) \hat{\mathbf{z}}$ on high density plasma resulting in low flow and \mathbf{B} field with field lines along contours of $|\mathbf{E}|$.

Step 2. Rescale n , fix \mathbf{B} and evolve T :

$$\frac{3}{2}n \frac{\partial T}{\partial t} = \kappa_{\perp} \nabla \cdot [(\mathbf{I} - \mathbf{b}\mathbf{b}) \cdot \nabla T] - \nabla \cdot \mathbf{q}_{\parallel} + Q_{\text{ext}}$$

where Q_{ext} has same spatial dependence as $|\mathbf{E}|$.

The resulting steady state has

$$\mathbf{B} \cdot \nabla T = 0$$

► Standard Fourier conduction: $\mathbf{q}_{\parallel} = -\kappa_{\parallel} (\mathbf{b} \cdot \nabla T) \mathbf{b}$

► Mixed finite element: $\theta \Delta \mathbf{q}_{\parallel} \rightarrow \bar{q}_{\parallel} \mathbf{b}$ where

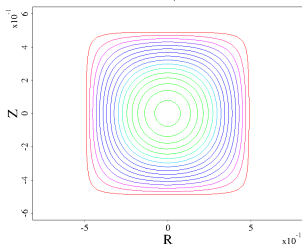
$$\bar{q}_{\parallel} + \theta \kappa_{\parallel} \mathbf{b} \cdot \nabla \Delta T = -\kappa_{\parallel} \mathbf{b} \cdot \nabla T^n$$

► Kinetic heat flux: $\mathbf{q}_{\parallel} = \frac{m}{2} \int d\mathbf{v} v^2 v_{\parallel} F$

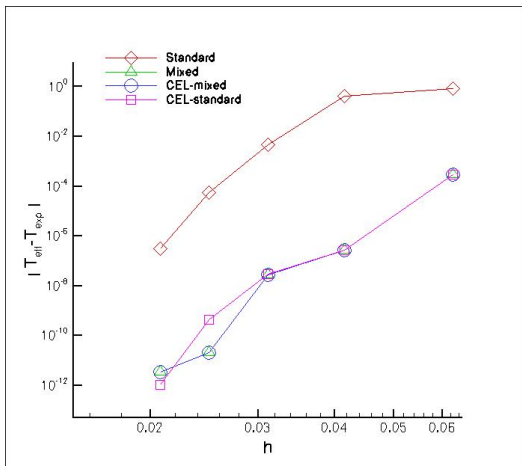
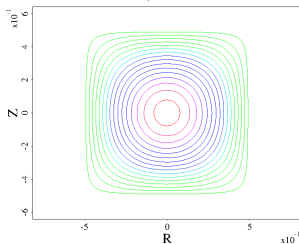
*C.R. Sovinec, *et al*, J. Comput. Phys. **195** (2004) 355–386

Staggered advance to steady state illustrates kinetic closure akin to mixed finite element

Poloidal flux, extrema= $(-5.063e-02, 1.583e-16)$



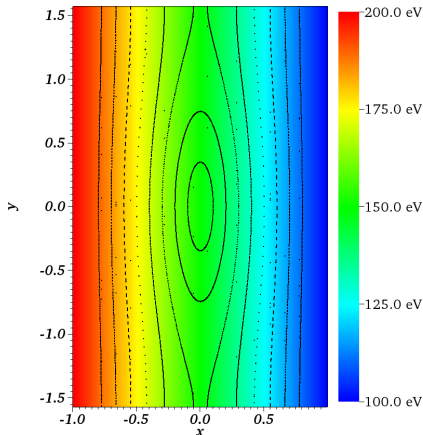
Re tele, extrema= $(2.000e+02, 1.200e+03)$



Test case 2: thermal transport in magnetic island

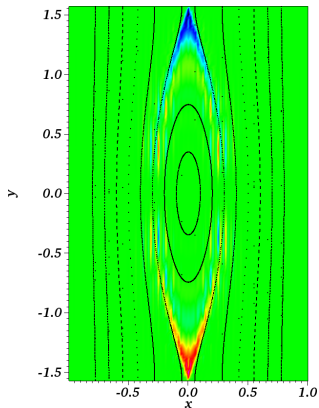
Kinetic parallel thermal transport across magnetic island in slab geometry

- ▶ $n = 9.5175 \times 10^{18} \text{ m}^{-3}$, $\mathbf{V} = 0$
- ▶ Ignore electron-ion and ion-electron collisions
- ▶ Boundary condition: periodic in Z direction
- ▶ Objective: take as large time steps as possible to get to steady state with kinetic parallel heat flux
- ▶ 32x32 grid in xy -plane
- ▶ 3rd degree polynomials

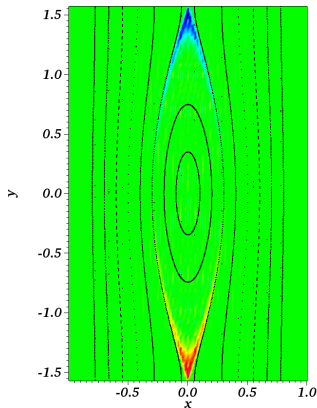
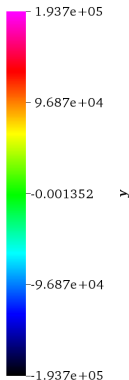


Initial temperature is a linear gradient that flattens across island as T evolves

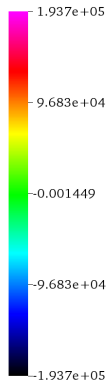
Standard and mixed finite element steady state parallel heat flux with conductivity $\kappa_{\parallel} = 1.5 \times 10^7$



Standard fluid steady state
 q_{\parallel} [W/m^2]



Mixed finite element steady state
 q_{\parallel} [W/m^2]



Review of Picard iterations

Goal: Integrate the nonlinear initial value problem

$$\mathbf{x}'(t) = \mathbf{g}(\mathbf{x}(t)), \quad \mathbf{x}(t_0) = \mathbf{x}_0$$

Where formal integration gives

$$\mathbf{x}(t) = \mathbf{x}_0 + \int_{t_0}^t \mathbf{g}(\mathbf{x}(s)) ds$$

Forward Euler method:

$$\mathbf{x}(t) = \mathbf{x}_0 + \Delta t \mathbf{g}(\mathbf{x}_0)$$

Backward Euler method:

$$\mathbf{x}(t) = \mathbf{x}_0 + \Delta t \mathbf{g}(\mathbf{x}(t))$$

Picard iterations: solve explicit equation iteratively to converge on solution to implicit equation

$$\mathbf{x}_{k+1} = \mathbf{x}_0 + \Delta t \mathbf{g}(\mathbf{x}_k)$$

How to apply Picard and Newton methods to our set of differential equations?

Implicit advance of F:

$$\begin{aligned} & \frac{F^{k+1} - F^k}{\Delta t} + \sqrt{\frac{2T}{m}} s\xi \left(\nabla_{\parallel} F^{k+1} - \frac{1 - \xi^2}{2\xi} \nabla_{\parallel} \ln B \frac{\partial F^{k+1}}{\partial \xi} \right) - \frac{s}{2T} \left(\sqrt{\frac{2T}{m}} s\xi \nabla_{\parallel} + \frac{\partial}{\partial t} \right) T \frac{\partial F^{k+1}}{\partial s} \\ & = C(T, F^{k+1}) + \left[\left(\frac{5}{2} - s^2 \right) \sqrt{\frac{2}{mT}} s\xi \nabla_{\parallel} T + \frac{2}{3nT} \left(s^2 - \frac{3}{2} \right) (\nabla \cdot \mathbf{q}_{\parallel} (F^{k+1}, T) - G) \right] f^M(T) \end{aligned}$$

Implicit advance of T:

$$\frac{3}{2} n \frac{T^{k+1} - T^k}{\Delta t} = \kappa_{\perp} \nabla \cdot [(\mathbf{I} - \mathbf{b}\mathbf{b}) \cdot \nabla T^{k+1}] - \nabla \cdot \mathbf{q}_{\parallel}(T, F) + G$$

Review of Newton's method

Goal: find zero of nonlinear $f(x)$ near x_0

- ▶ Approximate function with tangent line:

$$y(x) = f'(x_0)(x - x_0) + f(x_0)$$

- ▶ Find zero of tangent line, and iterate:

$$f'(x_i)(x_{i+1} - x_i) = -f(x_i)$$

Goal: find solution to nonlinear system $\mathbf{A}(\mathbf{x}) = \mathbf{b}$

- ▶ Let $\mathbf{f}(\mathbf{x}) = \mathbf{A}(\mathbf{x}) - \mathbf{b}$, and choose initial guess, \mathbf{x}_0 .

- ▶ Let $J_{ij}(\mathbf{x}) = \partial f_i / \partial x_j(\mathbf{x}) = \partial A_i / \partial x_j(\mathbf{x})$

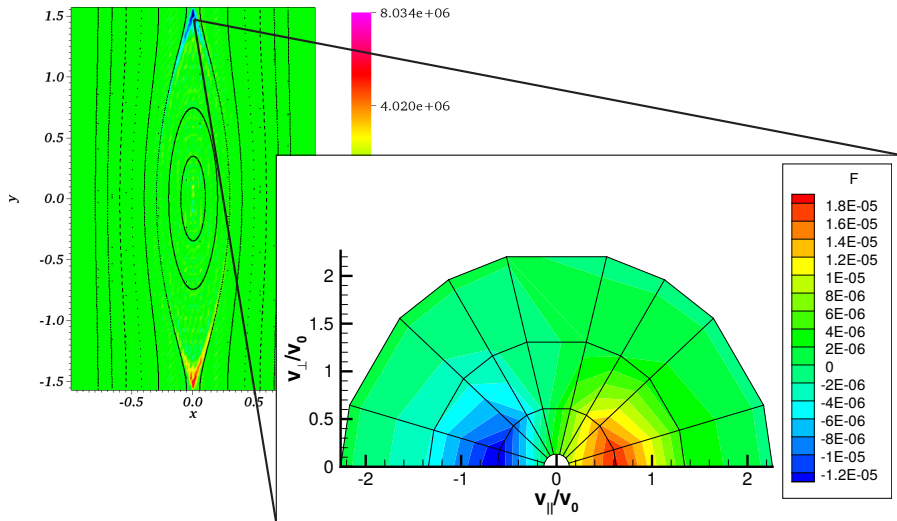
- ▶ Approximate \mathbf{f} with hyper-plane:

$$\mathbf{y}(\mathbf{x}) = \mathbf{J}(\mathbf{x}_0) \cdot (\mathbf{x} - \mathbf{x}_0) + \mathbf{A}(\mathbf{x}_0) - \mathbf{b}$$

- ▶ Find zeros of tangent lines, and iterate:

$$\mathbf{J}(\mathbf{x}_i) \cdot (\mathbf{x}_{i+1} - \mathbf{x}_i) = \mathbf{b} - \mathbf{A}(\mathbf{x}_i) \leftarrow \text{solved with preconditioned GMRES}$$

Kinetic heat flux calculated as moment of distribution function



Newton more costly than Picard iterations but can take larger time step

- ▶ 256 processors, 32x32 grid, polynomial degree=3
- ▶ Starting from MFE steady state run an additional 10^{-5} s

	Δt	wall clock time to $t = 10^{-5}$ s	average GMRES iterations per step	time per iteration
Picard	10^{-8} s	75 mins	5	0.9 s
Newton	10^{-8} s	200 mins	4	3 s
Newton	10^{-7} s	49 mins	52	0.57 s
Newton	10^{-6} s	42 mins	723	0.35 s
Newton	10^{-5} s	166 mins?	8207	1.2 s?

- ▶ Unoptimized algorithm leaves room for improvement

Upcoming work

- ▶ Implement s-parallelism for simultaneous advance
- ▶ Possibly speed-up Newton iterations
(reuse preconditioning matrix, improve check for convergence)
- ▶ Adaptive time step
- ▶ Examine needed velocity grid for electron-ion collisions
- ▶ Use developed code in a tearing mode simulation
with evolving \mathbf{B} , n , \mathbf{V} .